The Grainger College of Engineering



UNIVERSITY OF ILLINOIS URBANA-CHAMPAIGN

Target Site Selection

- Identify unprepared landing sites less vulnerable to PSI due to natural geology
- Inverse correlation between bulk density and erosion rate
- Use existing dielectric constant data from LRO & Chandryaan Locate sites with highest bulk density, estimated by dielectric
- constant
- Demonstrated with modified Campbell Model & LRO datasets (1)



(Bulk) Density vs. Permittivity (Dielectric Constant) Graph (2)



Hazard Relative Navigation

- Phased-array radar used as a scatterometer enacts process similar to **Terrain Relative Navigation (TRN)**
- Leveraging the extensive testing and validation of COTS automotive radars Operational in dark, shadowed, and
- illuminated regions on the lunar surface



Hazard Relative Navigation Logic Flowpath



Radar POV with overlayed dielectric constant map

Requirement 24 GHz Frequency Wavelength 12.5 mm 0 36x0 36 r 15-25 kg nated Total Mass Electronic Reamsteering eam-Angle Range 0-30 degrees 3.1-3.5 degree Beam Width Sumber of Elements **Total Power** 20 W Antenna Efficiency 30% **Transmit Power** 114.8 dBm Pulse Width 10 ns

Campbell Model Validation (3)

High-Level Radar Parameters



LRO Map from equivelant location



Phase 0:

Prior to launch, use existing radar data sets to map estimated regolith dielectric constant and bulk density to identify sites vulnerable to high erosion under PSI.

Phase 2:

Use the onboard phased array radar instrument to supplement pre-flight maps with higher resolution estimates. Identify potential hazards to landing due to poor surface characteristics for PSI. **Coordinate with the Precision Landing** & Hazard Avoidance (PL&HA) hazard maps to avoid hazards and reduce PSI.

Phase 4:

Phase 0:

Selection

Target Site

After surface operations are complete, the instrumentation system measures changes in landing site dielectric constant during the lander's ascent to study the effects of PSI during takeoff.

Phase 4:

Ascent

Phase 3:

Surface

Phase 3: The instrumentation system remains active during terminal descent, measuring changes in dielectric constant during active erosion to collect data and inform soil models.

Holistic Integration of Navigational Dynamics for Erosion Reduction



Phase 1:

A phased-array radar is used to image the surface underneath within the preselected landing zone during initial descent. Radar data transmitted and received in real-time during descent is compared against existing dielectric constant maps to ensure nominal radar performance and positioning.



0.175

0.150

 $\widehat{\mathbf{Q}}$ 0.125



- create hazard maps, showcasing cost of diverting to new landing site
- Radar outputs divert hazard maps in real-time during descent Hazard maps from multitude of HDA sensors onboard the lander, including HINDERs' maps, are fused together