

Microgravity Blood Infusion Pump

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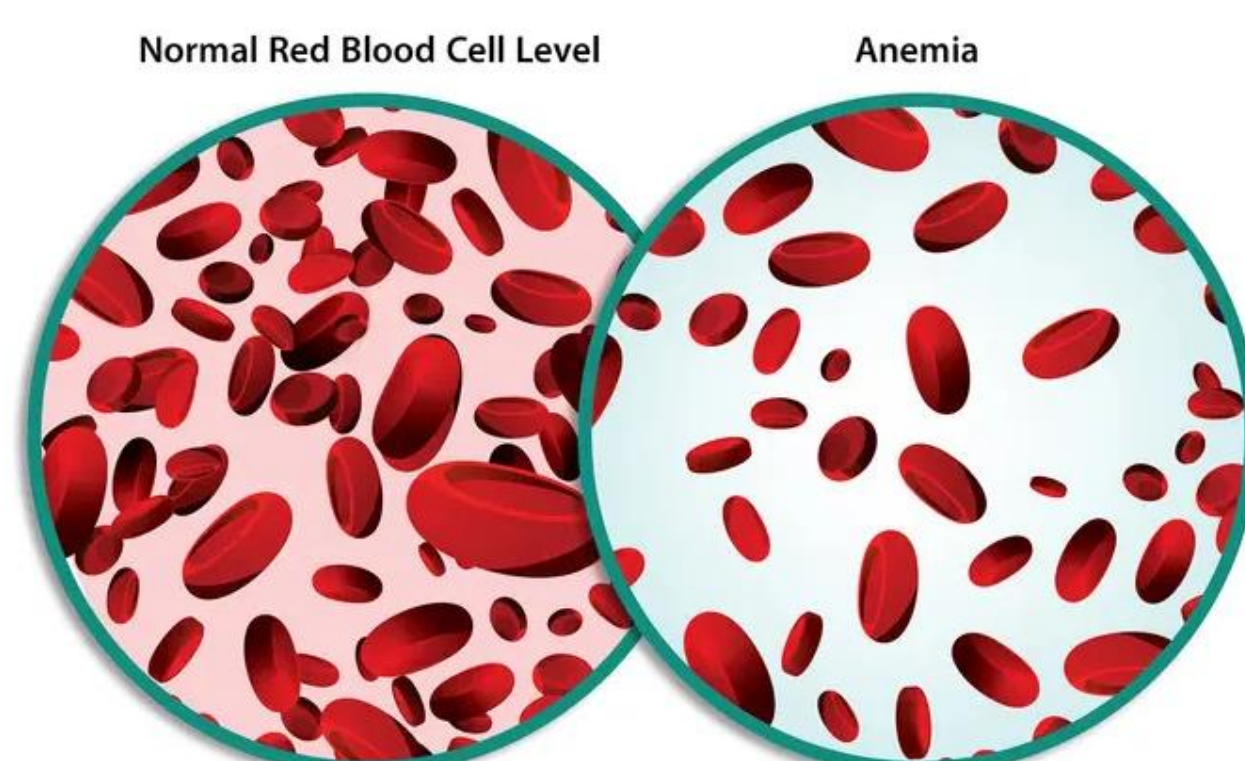
Background & Motivation

NASA's Artemis program extends human missions to 30 days on the Moon and up to 1,200 days for Mars transit, distances where medical evacuation is impossible. As more people live and work in space for long durations, the risk of severe hemorrhage or anemia becomes a critical concern. Blood transfusion can be a life-saving treatment, but no such solution currently exists for the microgravity environment. Conventional infusion systems rely on gravity-assisted flow and buoyancy-driven air separation, in microgravity, surface tension dominates fluid behavior, leaving gas bubbles suspended in the fluid path and creating serious air embolism risk. Even bubbles as small as 20 μL can be clinically dangerous.

Freeze-dried blood is the leading storage strategy for long-duration missions, and parabolic flight research has confirmed that rehydration in microgravity is feasible (Elder, 2024), but rehydration introduces air bubbles into the fluid line (Gao, 2025). Peristaltic pumps have also been demonstrated successfully moving IV fluid in microgravity (Spaulding, 2004), validating the core pumping mechanism. However, no integrated system exists that combines gravity-independent pumping with active bubble removal and detection.

The MBIP addresses that gap directly.

The Medical Need



Anemia — reduced red blood cell count impairs oxygen delivery, worsened by known space-induced physiological changes. Red blood cells die 54% faster (Sohn, 2022). Symptoms include fatigue, shortness of breath, dizziness, and impaired cognitive function, dangerous for a crew operating complex systems far from Earth.

Hemorrhage — traumatic blood loss can reach critical levels within minutes

System Design

Microgravity Blood Infusion Pump

Peristaltic pump + ePTFE bubble trap + sensor suite = safe blood infusion in 0g and low gravity environments

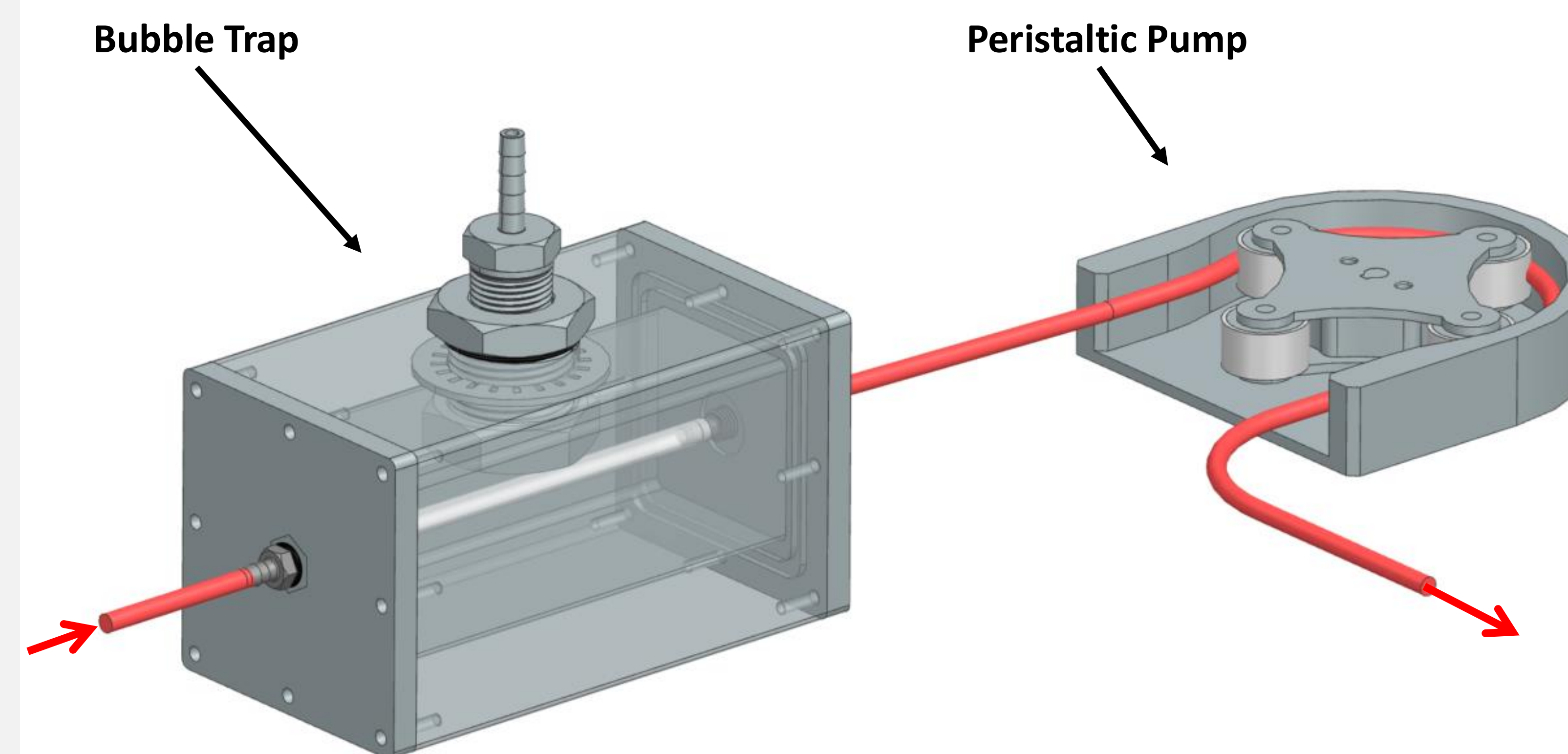
Gravity-independent flow — Peristaltic positive displacement replaces passive drip, operating across 0g, partial-g, and 1g environments.

Dual-layer bubble safety — ePTFE membrane passively removes bubbles; ultrasonic sensor triggers auto-shutoff for any remaining air $\geq 20 \mu\text{L}$.

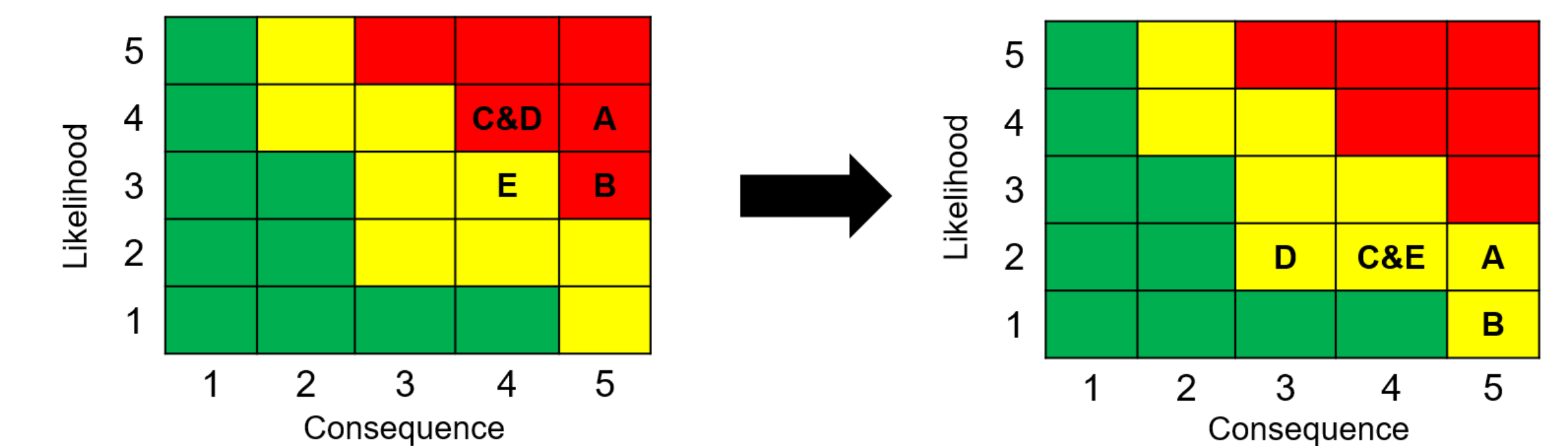
Closed-loop autonomy — Real-time flow, pressure, and battery monitoring within spacecraft mass, volume, and power constraints.

Specs: 400–500 mL/transfusion · 100–250 mL/hr flow rate · <3 W continuous · 4.56 lb total mass · 512 in³ stowed volume

Microgravity Blood Infusion Pump Assembly



Risk Analysis



ID	RISK	MITIGATION
A	Air Embolism	ePTFE trap + dual bubble sensors
B	Breach in Sterile Fluid Path	Closed, sterile disposable tubing set
C	Loss of Blood Delivery Capability	Motor torque margin + endurance validation testing
D	Vacuum Pump / Pressure Seal Failure	Pressure monitoring + leak testing protocol
E	Hemolysis	Peristaltic pump selection, compliant tubing + low speeds

Prototype Cost Breakdown

Component	Cost (USD)
BLDC Motor	\$14
Vacuum Pump (KNF NMP 830)	\$320
Arduino Microcontroller	\$28
LiFePO ₄ Battery (3Ah)	\$32
Tubing & Connectors	\$100
ePTFE Membrane Cartridge	\$120
Metal Pump Housing	\$100
Polycarbonate Housing	\$100
Ultrasonic Bubble Detector	\$250
Vacuum Pressure Sensor	\$30
Load Cell	\$15
Leak Detection Sensors	\$20
MEMS Accelerometer	\$20
Temperature Sensors	\$20

Hardware Subtotal

\$1,169

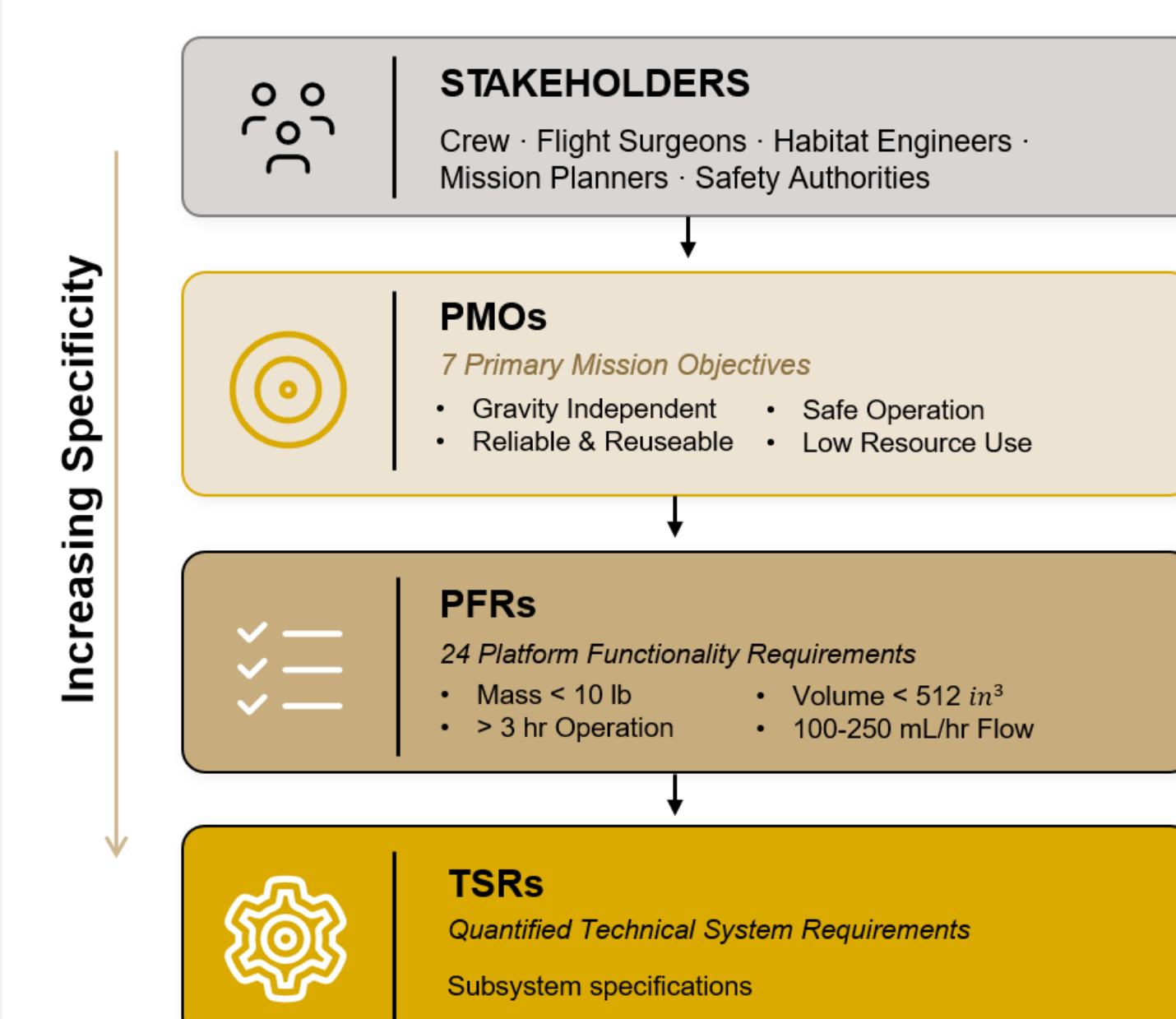
Testing & Contingency (~20%)

\$234

Total Prototype Cost

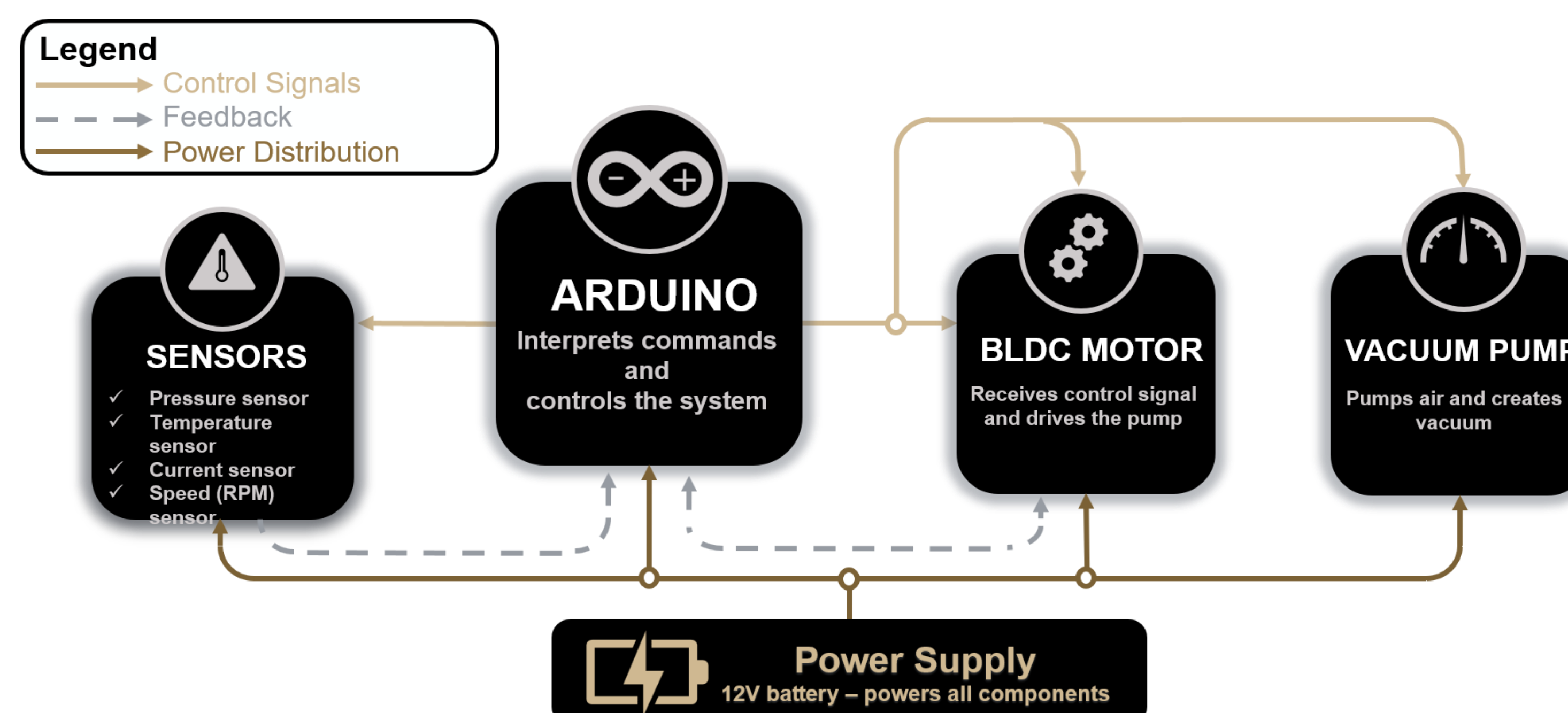
\$1,403

Requirements & Systems Engineering



KEY DESIGN DRIVERS	
PMO-3 Safety	Air $\geq 20 \mu\text{L}$ shutoff Hemolysis Index < 0.8%
PFR-11 Mass	< 10 lb total system mass
PFR-12 Volume	$\leq 512 \text{ in}^3$ stowed volume
PFR-24 Flow Rate	100-250 mL/hr

Arduino Control System



Future Steps

Lab Prototype Years 0-1	Integrate pump, bubble trap & control; validate flow accuracy & bubble detection; >3 hr endurance demo	TRL 3 → 4
Environmental Testing Years 1-3	Vibration & thermal cycling; parabolic flight validation of bubble removal & flow at 0g	TRL 4 → 5
Flight Engineering Model Years 5-6	Structural hardening, radiation-tolerant electronics; spacecraft power bus interface; integrated flight-like testing	TRL 5 → 6
Qualification & Integration Years 5-8	Qualification-level vibration & shock; hazard & safety certification; Artemis mission deployment readiness	TRL 6 → 7/8

★ Current Status: TRL 2-3 — Analytical modeling complete, motor control validated, prototype build in progress