



AggieSat Laboratory

Synthetic Orbital Landing Area for Crater Elimination (SOLACE)



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Program Manager: Shirish Pandam, B.S. (G, AERO)

Project Manager: Kamalika Bose (UG, MXET)

Chief Engineer: Nicholas X. Siodlarz, B.S. (G, BUSI)

06/26/24

Personnel

Command and Data Handling

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Guidance, Navigation, and Control

Lead: Travis Mason, (UG, AERO)
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Thermal, Mechanics, and Structures

Lead: Thomas Magee, (UG, AERO, PHYS)
Brandon Elliott, (UG, AERO)
Theresa Heimer, (UG, ITED)
Pan Zhou, (UG, MEEN)

Key

UG - Undergraduate
G - Graduate

AERO - Aerospace Engineering
CPEN - Computer Engineering
ECEN - Electrical Engineering
ESET - Electronic Systems and Engineering Technologies
ENGR - General Engineering
GEOG - Geography
ITDE - Interdisciplinary Engineering
MATH - Mathematics
MEEN - Mechanical Engineering
MXET - Mechatronics Engineering
PHYS - Physics

About AggieSat Laboratory

- *“The AggieSat Laboratory Student Space Program trains university students in systems engineering through hands-on experience in the design, building, testing, and operation of space-related systems.”*
- Largest university satellite program in the country
- 7 simultaneous projects this year
- AggieSat 6 – oldest project
- SOLACE – youngest project



Presenting: Shirish Pandam (Program Manager)

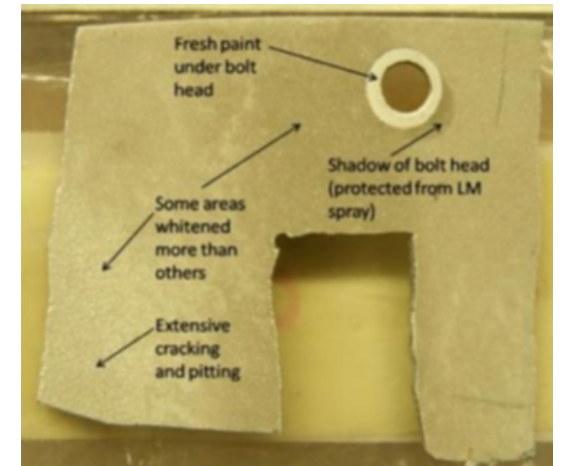


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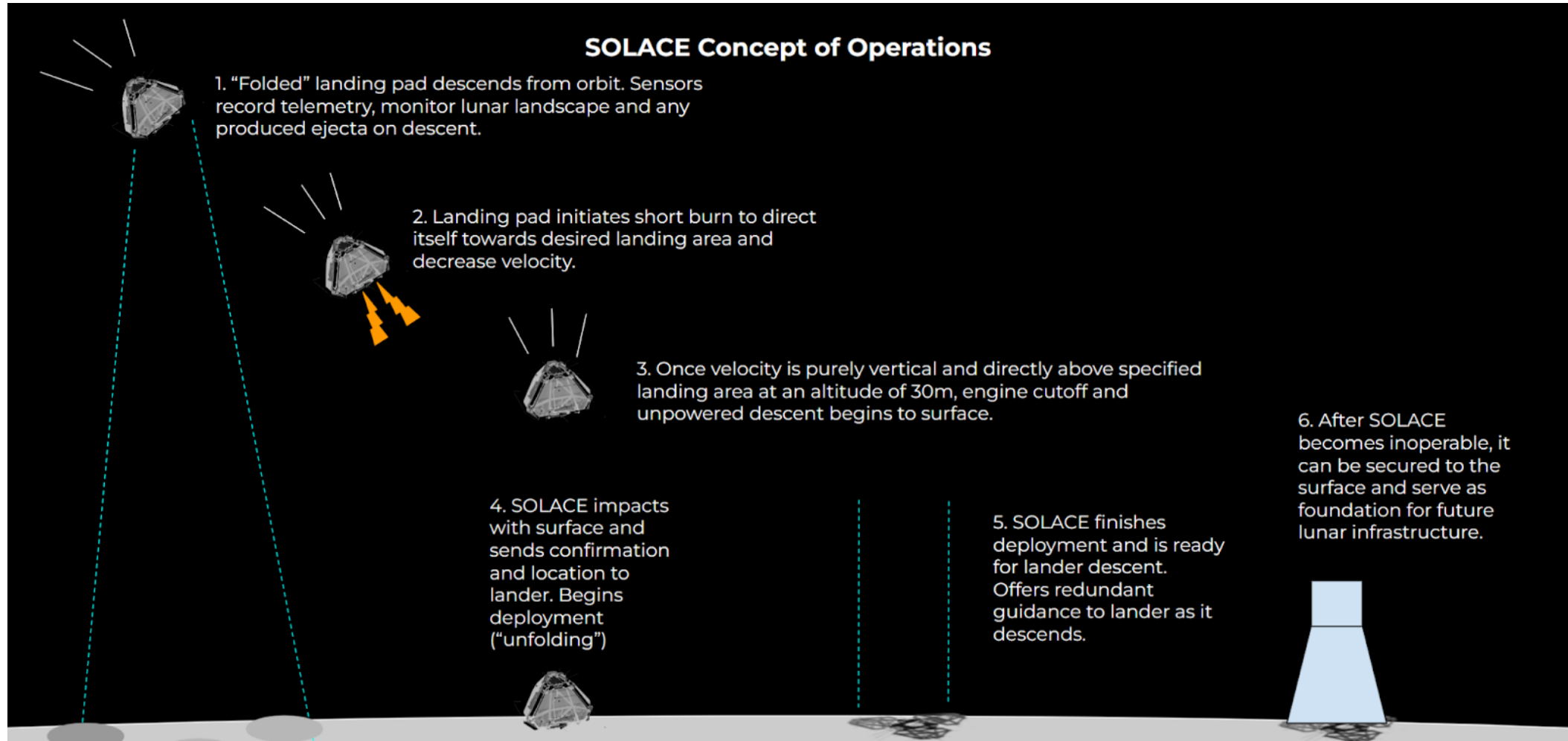
PSI-Induced Cratering and Dispersal

- Cratering: removal of local regolith to form “craters” in the surface
- Dispersal: dust and rocks blown from the landing site at high speeds
- Notable problems caused in previous planetary missions
 - Apollo missions: Engine overpressure, false velocity readings
 - Apollo 12 and *Surveyor III*: Damage to *Surveyor III* from regolith sandblasting
 - Mars Science Laboratory (MSL) and *Curiosity*: Damage to *Curiosity* from MSL’s descent
- Hard to characterize
 - Best testbed is the Moon
 - Only rudimentary predictions at best of important characteristics



Images courtesy of Zanon, et al

SOLACE Overview



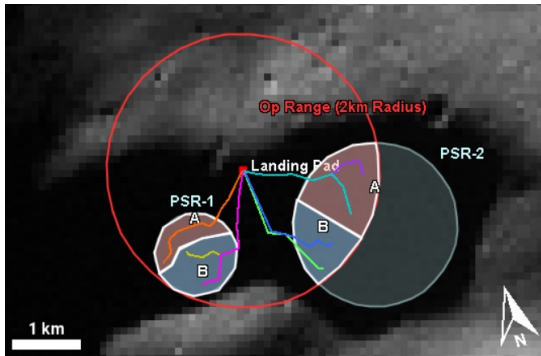
Presenting: Kamalika Bose (Project Manager)



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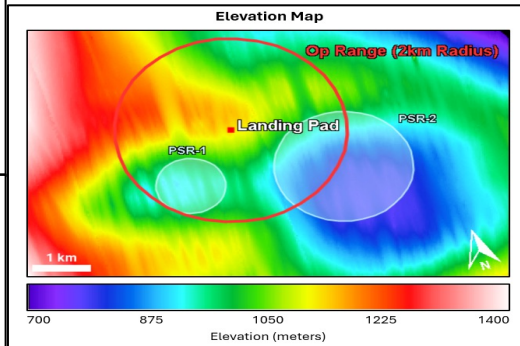
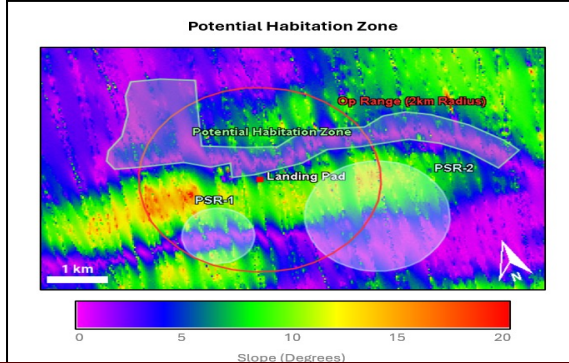
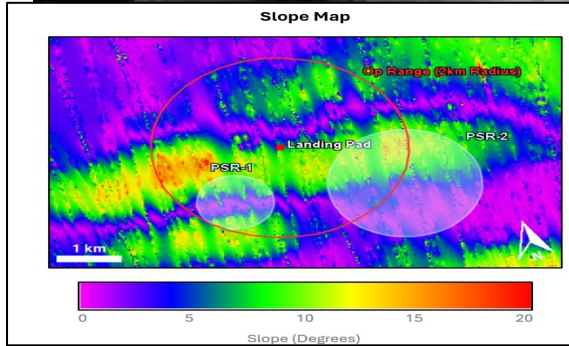
System Integration and Test Environment (SITE)

PSR Region Pathing

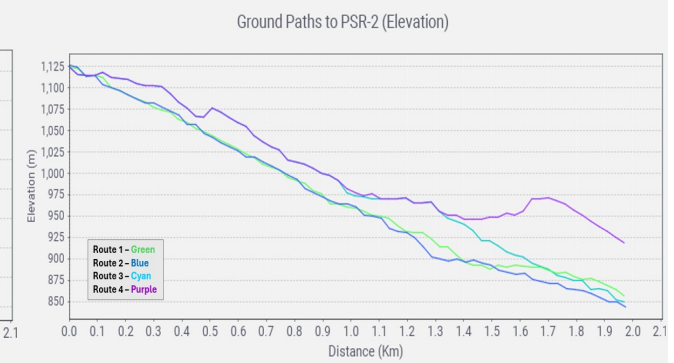
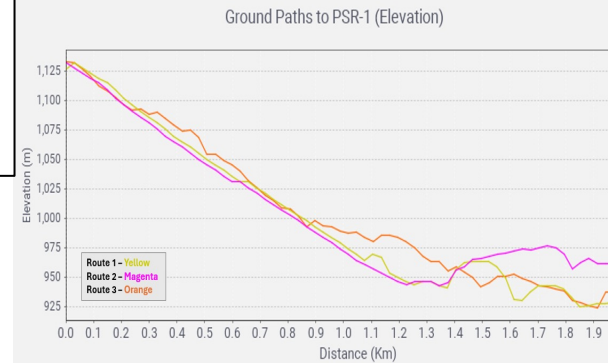
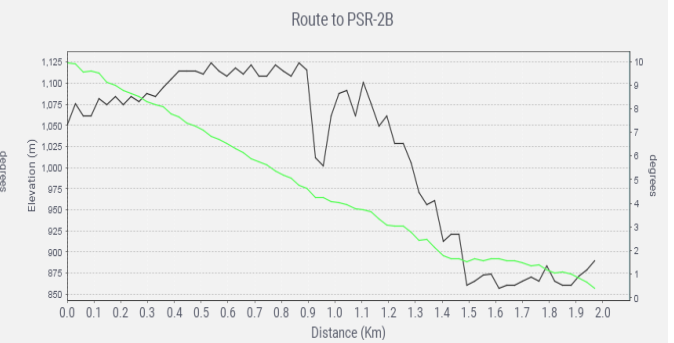
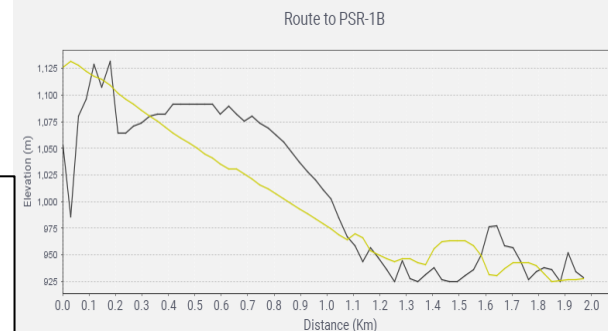
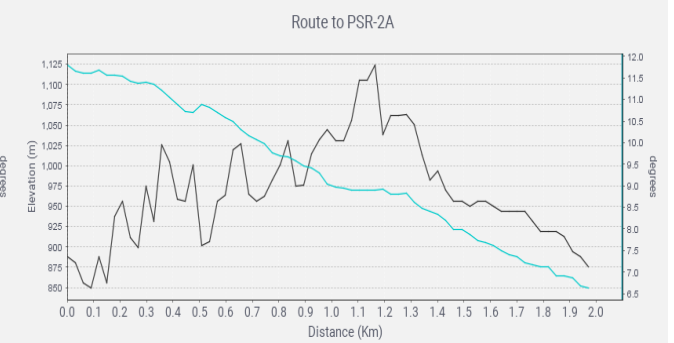
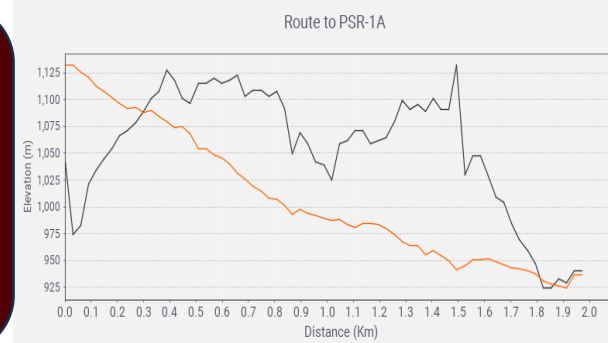


Artemis III Landing Region:
HAWORTH

Landing Site Coordinate:
 $-86.50757^{\circ}\text{N}$, $342.98057^{\circ}\text{E}$



Images found using JMARS



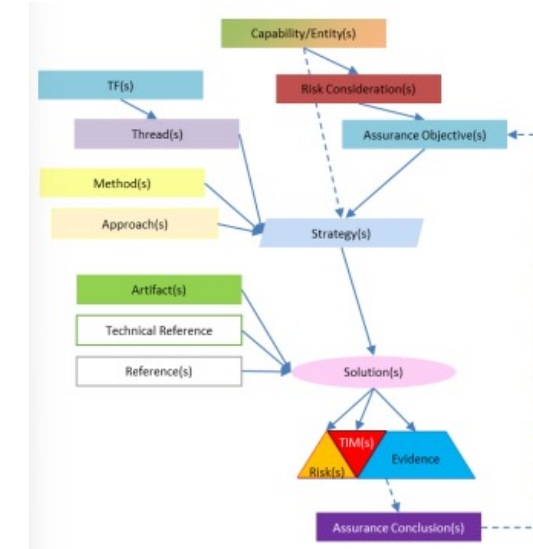
Presenting: Kamalika Bose (Project Manager)

System Integration and Test Environment (SITE)

Adaptive Independent Verification and Validation Plan

Particle and PSI Analysis

Compound	Insoluble or soluble in Water	Chemical Reactivity	Density	Compound	Weight percent in Lunar Regolith	Most Common Form
Silicone Dioxide	Insoluble	Non - Reactive	2.65 g/cm ³	Silicone Dioxide	42-48%	Transparent to gray powder
Titanium Dioxide	Insoluble	Non - Reactive	4.23 g/cm ³	Titanium Dioxide	1-7%	Odorless white powder
Aluminum Oxide	Insoluble	Non - Reactive	3.99 g/cm ³	Aluminum Oxide	12-27%	Crystalline powder (corundum)
Iron Oxide	Insoluble	Reactive	5.74 g/cm ³	Iron Oxide	4-18%	Reddish-brown powder
Magnesium Oxide	Practically insoluble	Reactive	3.58 g/cm ³	Magnesium Oxide	4-11%	White nanopowder
Calcium Oxide	Soluble	Reactive	3.34 g/cm ³	Calcium Oxide	10-17%	Odorless white amorphous powder
Sodium Oxide	Insoluble	Reactive	2.27 g/cm ³	Sodium Oxide	0.4-0.7%	Odorless white powder
Potassium Oxide	Insoluble	Reactive	2.27 g/cm ³	Potassium Oxide	0.1-0.6%	Yellow or white odorless crystalline solid compound
Manganese(II) Oxide	Insoluble	Reactive	5.37 g/cm ³	Manganese(II) Oxide	0.1-0.2%	Greenish powder
Chromic Oxide	Insoluble	Non - Reactive	5.22 g/cm ³	Chromic Oxide	0.2-0.4%	Fine light to dark green hexagonal crystals



	Mechanical similarity to regolith	Mineralogical similarity to regolith	Availability	Cost	Lunar ISRU simulatability	Total Score
Weight	5	5	3	3	4	
JSC-1	4	2	1	1	2	10
LHS-1	5	5	4	2	4	20
NU-LHT-2	4	3	4	4	2	17
Weighted Scores						
JSC-1	20	10	3	3	8	44
LHS-1	25	25	12	6	16	84
NU-LHT-2	20	15	12	12	8	67

Scale	1	Poor
	2	Below Average
	3	Average
	4	Above Average
	5	Excellent

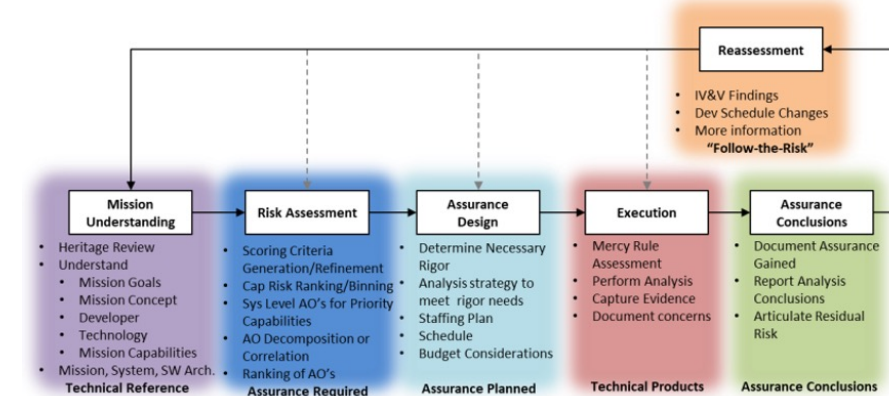
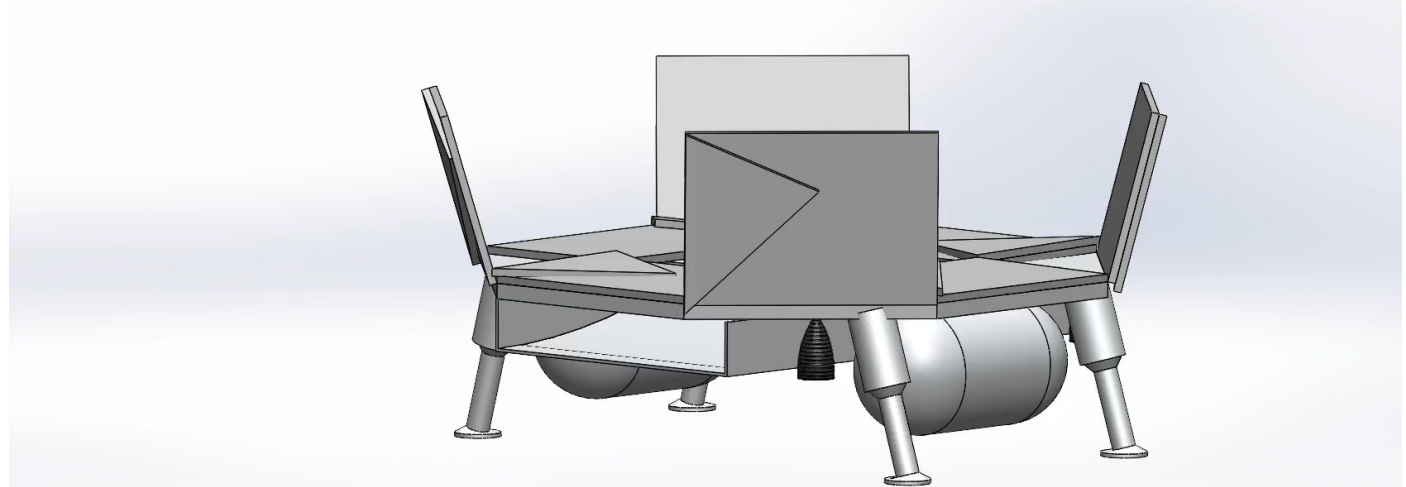


Image courtesy of NASA IV&V Program

Presenting: Kamalika Bose (Project Manager)

Thermal, Mechanics, and Structures (TMS)

- “Bunker”-esque design
 - Lower base – houses electrical components and other sensitive equipment
 - Plume redirection system – redirects plume to one specific line of redirection
 - Grating – aids in nozzle plume redirection
 - Main landing surface – consists of 18 parts that can be stowed or deployed
 - Spring-actuated “stakes” – inject into lunar surface for pad stability on HLS descent
- Materials
 - Graphene
 - Titanium aluminide
 - Hafnium diboride



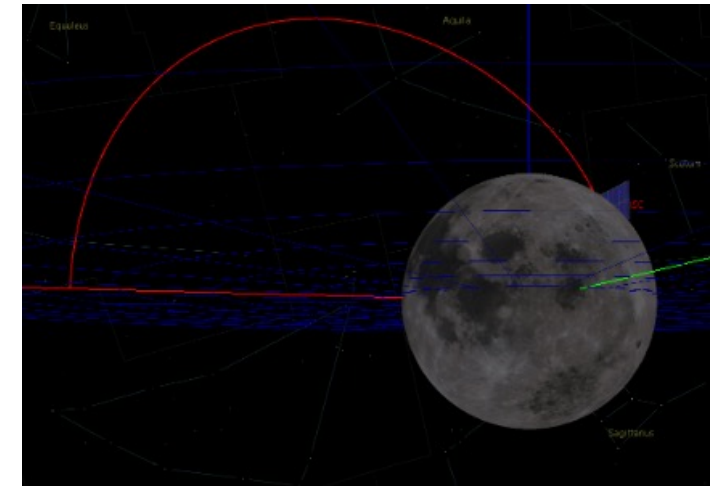
Thermal, Mechanics, and Structures

- Propulsion
 - Four liquid-propelled boosters provide descent and attitude control
 - Engine gimbals
 - Enable attitude control
 - Gimbal to lunar parallel to limit PSI on descent
 - Methalox was chosen over hydrazine
- Overall characteristics
 - Dry mass of 14.38 metric tons
 - Wet mass of 25.38 metric tons
 - Stands 1.4 m tall, occupies a total volume of 18.28 m³
 - Pad landing surface can withstand temperatures up to 3600 K
 - Pad can withstand loads up to 162 kN

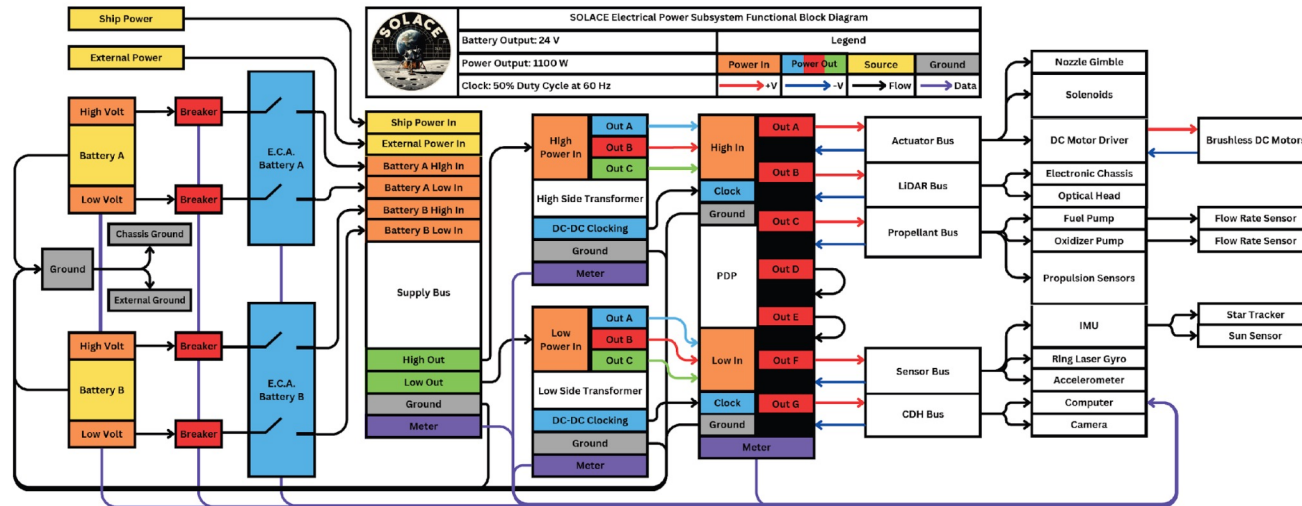


Guidance, Navigation, and Control (GNC)

- Guidance System
 - Employs a novel machine learning algorithm trained on previous lunar landing videos
 - Identifies safe landing zones on descent
 - Identifies abort trajectories in the event of off-nominal scenarios
 - Nominal trajectory analyzed in NASA General Mission Analysis Toolkit (GMAT)
- Navigation System
 - IMU – Honeywell HG1900 IMU
 - LiDAR – NASA's Navigational Doppler LiDAR
 - Star tracker – RocketLab ST 16HV star tracker
 - Sun sensor – RedWire Coarse Sun Sensor (Cosine Type)
- Control System
 - Gimballing boosters can be used for attitude and descent control



Electrical Power Subsystem (EPS)



System	Component	Manufacturer	Power	Voltage	Current	Quantity
Sensor Array	Navigation Doppler Lidar	NASA Langley	80 W	28 VDC	2.857 A	1
	GG1320 Ring Laser Gyro	Honeywell	1.6 W	15 VDC	0.107 A	1
	HG1900 IMU	Honeywell	3 W	5 VDC	0.6 A	1
	Coarse Sun Sensor	RedWire	0 W	TBD	0.0013 A	1
	ST-16HV Star Tracker	RocketLab	0.5 W - 1 W	9 - 34 VDC	0.056 A (MAX)	1
	TMP64 Thermistor	Texas Instruments	0 W	5.5 VDC	0.0 A	4
	Accelerometer	NASA JPL / UCLA	0.058 W	TBD	TBD	1
Computer	Jetson AGX Orin	NVIDIA	15 - 60 W	12 VDC	5.0 A (MAX)	1
	IMX586 Camera	ArduCam	1.19 W	5 VDC	0.238 A	1
Control	PD82152B BLDC Motor	Transmotec	120 W	24 VDC	7.2 A	4
	SDU-.75 WA Solenoids	Moog	10 W	24 VDC	0.42 A	16
	MCF8315C Driver	Texas Instruments	1 W	4 - 35 VDC	4.0 A	4
Propulsion	Fuel Pump	NASA Glenn	500 W	TBD	TBD	4
	Oxidizer Pump	NASA Glenn	500 W	TBD	TBD	4
	Gimble	NASA Marshall	TBD	TBD	TBD	4
Totals:			4790.848 W (MAX)			

EPS Key Features:

- ? External power plug-ins and permanent grounding capability
- ? DC-DC clocking for PWM
- ? Metering at each stage for monitoring
- ? Dedicated busses for other subsystems
- ? Transformers to provide a wide range of potential input voltages

EPS Sensor Array:

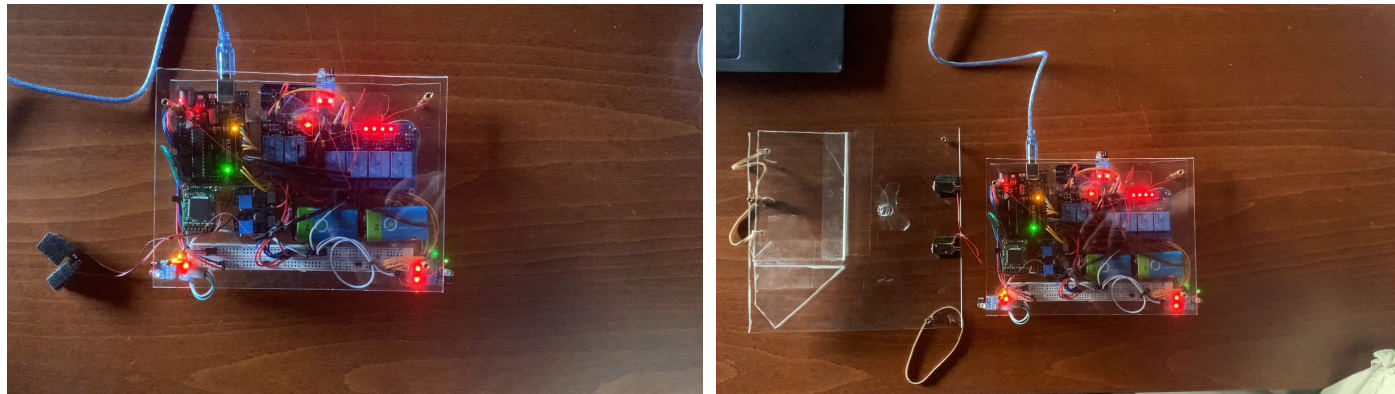
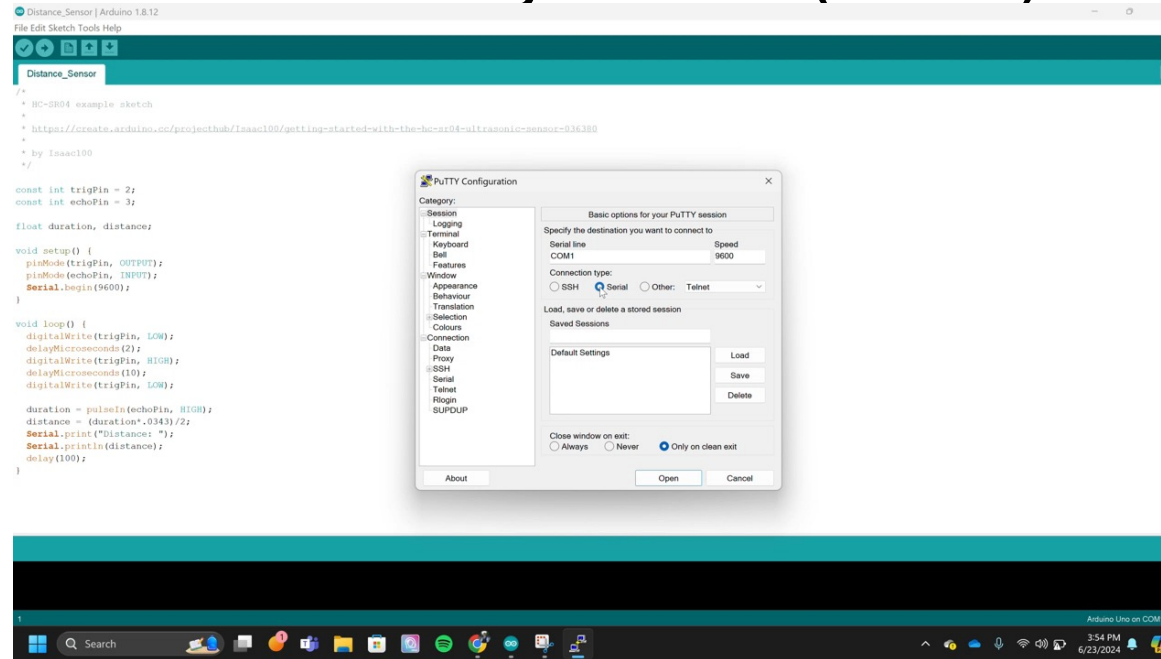
- ? NASA Navigational Doppler Lidar
- ? Honeywell Ring Laser Gyro
- ? Honeywell IMU
- ? RedWire Sun Sensor
- ? RocketLab Star Tracker
- ? Texas Instruments Thermistors
- ? NASA Designed Accelerometers

EPS Mechanical:

- ? Transmotec Brushless DC Motors
- ? Moog Solenoids
- ? Texas Instruments DC Motor Drivers
- ? NASA Designed Propulsion Gimbels
- ? NASA Designed Propulsion Pumps

Presenting: Thomas Lopez (EPS Lead)

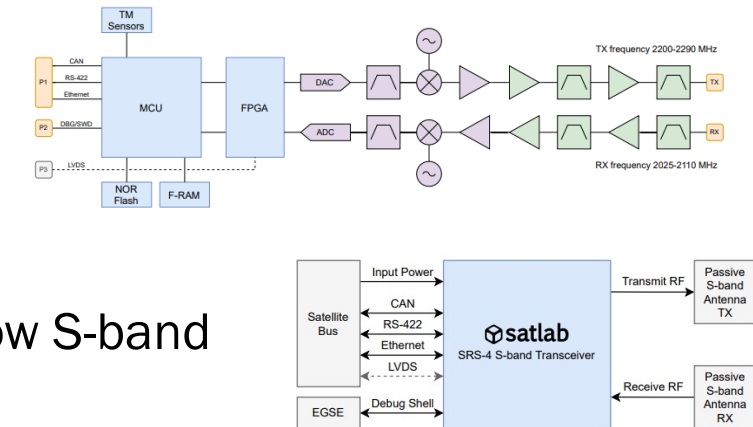
Electrical Power Subsystem (EPS)



Presenting: Thomas Lopez (EPS Lead)

Communications (COM)

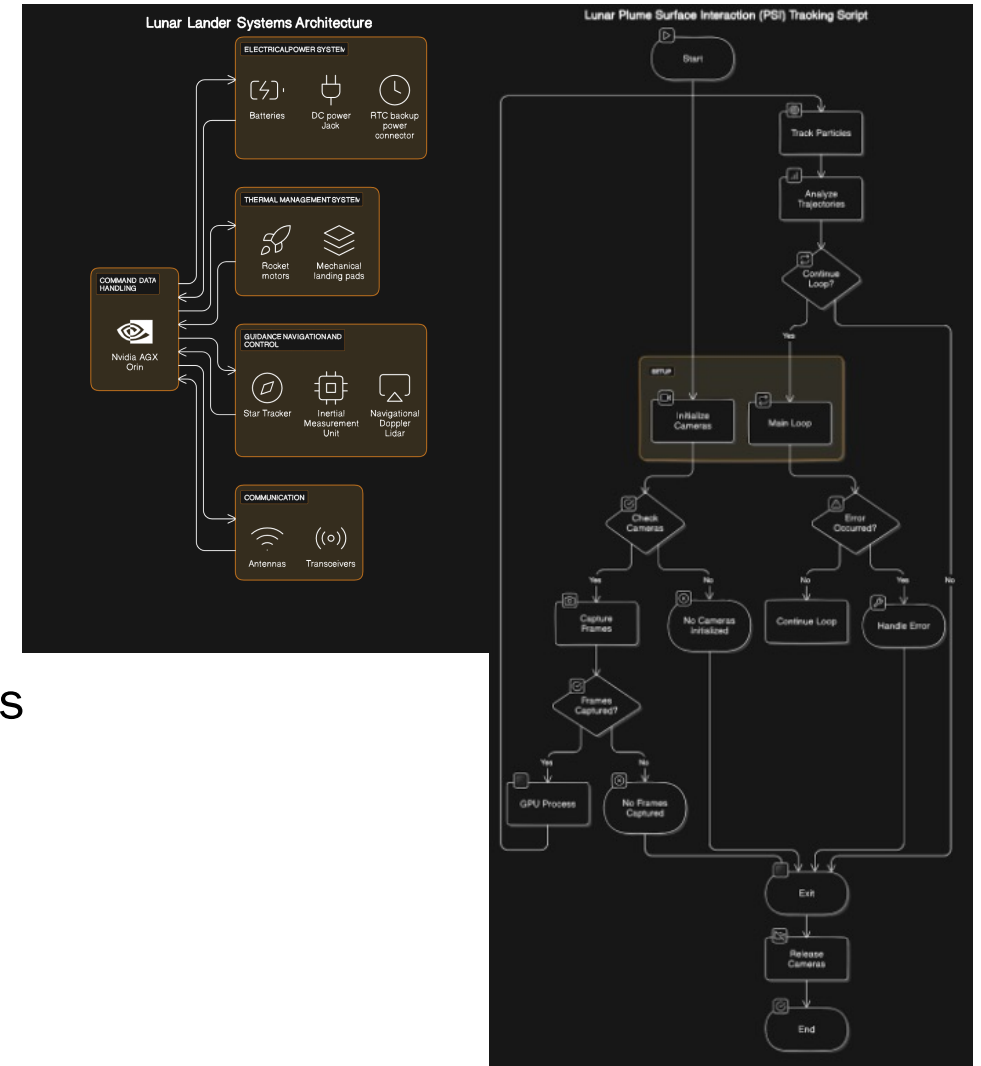
- **SRS-4 Full-Duplex High-Speed S-Band Transceiver**
 - Operates on ITU-approved S-Band frequencies centered at 2250 MHz
 - 16-QPSK modulation scheme with compatibility for CCSDS channel coding
 - Variable transmit symbol rate up to 10 MB/s
 - Bitrate up to 12.5 MB/s when communicating with NVIDIA Jetson Nano
 - Average power output of 4W at a gain of 9 dBi, max gain of 11 dBi
- **IQ-Spacecom S-Band Patch Antenna**
 - Designed to operate at a center frequency of 2250 MHz with max 11 dBi gain
 - 50 MHz bandwidth
- **Lunar Environmental Impacts**
 - Lunar Regolith Permittivity: 3 F/m
 - Conductivity: $10E-14$ S/m Sun, $10E-9$ S/m dark
 - 5-10 dB estimated loss
 - Lunar ground acts as a reflector and absorber below S-band



Images courtesy of SatLab SRS-4 data sheet.

Command and Data Handling (CDH)

- Components
 - NVIDIA Jetson AGX Orin
 - 3 ArduCam IMX586 48MP Camera Modules
- Hierarchical State Machine (HSM)
 - Reacts to asynchronous and nondeterministic inputs
 - Structured and flexible management framework
- PSI Monitoring
 - 3D particle tracking velocimetry
 - Cameras rotate to lunar parallel once descent has been completed



Presenting: Nicholas Siodlarz (Chief Engineer)

System Merit

- Performance
 - Adheres to HuLC constraints and guidelines
 - Unique position to act as a testbed for emerging technologies, such as machine-learning driven guidance
- Technology Readiness
 - Most incorporated technologies are TRL 9
- Risk
 - Low risk solution
 - Anticipated risks were analyzed, and mitigation strategies were developed
- Programmatic Implementation
 - Designed to be compatible with any proposed HLS or other landing system
 - Designed to function nominally in a wide variety of lunar regions

		Severity				
		Insignificant	Minor	Moderate	Major	Severe
Likelihood	Almost Certain					
	Likely			4		
	Possible			2	5	1, 3
	Unlikely		3f, 5f	1f		
	Rare	4f	2f			

1: SOLACE is a projectile
 2: Accelerated degradation
 3: Failed deploy
 4: Descent brownout
 5: Departs from trajectory

1f: Stakes
 2f: Titanium aluminide
 3f: Spring-loaded actuators
 4f: Robust regulation
 5f: Intelligent aborts

Costing

- Total estimated cost of SOLACE's lifetime development, launch, and operations is \$1944.9M
 - \$290.5M for non-recurring costs (NRC)
 - \$1051.8M for recurring production costs
 - \$189.9M for launch and \$370.2M for operations
 - Values calculated with NASA's Project Cost Estimation Capability (PCEC)

Synthetic Orbital Landing Area for Crater Elimination (SOLACE) Lifetime Cost Estimation												
FY2024 \$M			Units Conversion Factor: 1.000 Inflation Factor: 1.187									
WBS #	Level	Line Item Name/Description	Non-Recurring	Design & Development	System Test Hardware	Flight Unit	Recurring Production	Non-Allocated	Operations	TOTAL	Fee + Burden	TOTAL w/Fee + Burden
0	1	System Name	\$ 290.5	\$ -	\$ -	\$ -	\$ 1,051.8	\$ 232.4	\$ 370.2	\$ 1,944.9	\$ -	\$ 1,944.9
1.0	2	Project Management	\$ 19.1	\$ -	\$ -	\$ -	\$ 44.4	\$ -	\$ -	\$ 63.5	\$ -	\$ 63.5
2.0	2	Systems Engineering	\$ 10.6	\$ -	\$ -	\$ -	\$ 17.1	\$ -	\$ -	\$ 27.6	\$ -	\$ 27.6
3.0	2	Safety and Mission Assurance	\$ 15.5	\$ -	\$ -	\$ -	\$ 34.0	\$ -	\$ -	\$ 49.5	\$ -	\$ 49.5
4.0	2	Science/Technology	\$ -	\$ -	\$ -	\$ -	\$ -	\$ 42.6	\$ -	\$ 42.6	\$ -	\$ 42.6
5.0	2	Payload(s)	\$ 7.1	\$ -	\$ -	\$ -	\$ 15.6	\$ -	\$ -	\$ 22.7	\$ -	\$ 22.7
5.01	3	Payload Management	\$ 2.5	\$ -	\$ -	\$ -	\$ 5.8	\$ -	\$ -	\$ 8.3	\$ -	\$ 8.3
5.02	3	Payload System Engineering	\$ 0.8	\$ -	\$ -	\$ -	\$ 1.3	\$ -	\$ -	\$ 2.1	\$ -	\$ 2.1
5.03	3	Payload Product Assurance	\$ 0.3	\$ -	\$ -	\$ -	\$ 0.8	\$ -	\$ -	\$ 1.1	\$ -	\$ 1.1
5.10	3	Instruments - EMPTY ROLLUP	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -
5.x	3	Payload I&T	\$ 3.5	\$ -	\$ -	\$ -	\$ 7.7	\$ -	\$ -	\$ 11.2	\$ -	\$ 11.2
6.0	2	Flight System \, Spacecraft	\$ 190.3	\$ -	\$ -	\$ -	\$ 810.6	\$ -	\$ -	\$ 1,000.9	\$ -	\$ 1,000.9
6.01	3	Flight System Project Management	\$ 1.0	\$ -	\$ -	\$ -	\$ 2.3	\$ -	\$ -	\$ 3.3	\$ -	\$ 3.3
6.02	3	Flight System Systems Engineering	\$ 1.8	\$ -	\$ -	\$ -	\$ 2.9	\$ -	\$ -	\$ 4.7	\$ -	\$ 4.7
6.03	3	Flight System Product Assurance	\$ 4.6	\$ -	\$ -	\$ -	\$ 10.0	\$ -	\$ -	\$ 14.6	\$ -	\$ 14.6
6.10	3	Spacecraft	\$ 168.1	\$ -	\$ -	\$ -	\$ 762.6	\$ -	\$ -	\$ 930.7	\$ -	\$ 930.7
--	4	Structures & Mechanisms	\$ 18.0	\$ -	\$ -	\$ -	\$ 670.3	\$ -	\$ -	\$ 688.3	\$ -	\$ 688.3
--	4	Thermal Control	\$ 0.1	\$ -	\$ -	\$ -	\$ 0.0	\$ -	\$ -	\$ 0.1	\$ -	\$ 0.1
--	4	Electrical Power & Distribution	\$ 1.4	\$ -	\$ -	\$ -	\$ 1.1	\$ -	\$ -	\$ 2.5	\$ -	\$ 2.5
--	4	GN&C	\$ 0.5	\$ -	\$ -	\$ -	\$ 0.7	\$ -	\$ -	\$ 1.2	\$ -	\$ 1.2
--	4	Propulsion	\$ 142.2	\$ -	\$ -	\$ -	\$ 84.4	\$ -	\$ -	\$ 226.6	\$ -	\$ 226.6
--	4	Communications	\$ 0.9	\$ -	\$ -	\$ -	\$ 1.2	\$ -	\$ -	\$ 2.1	\$ -	\$ 2.1
--	4	C&DH	\$ 5.0	\$ -	\$ -	\$ -	\$ 4.9	\$ -	\$ -	\$ 9.9	\$ -	\$ 9.9
6.x	3	Flight System I&T	\$ 14.9	\$ -	\$ -	\$ -	\$ 32.8	\$ -	\$ -	\$ 47.6	\$ -	\$ 47.6
7.0	2	Mission Operations System (MOS)	\$ 19.2	\$ -	\$ -	\$ -	\$ 66.9	\$ -	\$ 370.2	\$ 456.3	\$ -	\$ 456.3
--	3	MOS/GDS Development (Phase B-D)	\$ 19.2	\$ -	\$ -	\$ -	\$ 66.9	\$ -	\$ -	\$ 86.1	\$ -	\$ 86.1
--	3	Mission Ops & Data Analysis (Phase E)	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ 370.2	\$ 370.2	\$ -	\$ 370.2
8.0	2	Launch Vehicle/Services	\$ -	\$ -	\$ -	\$ -	\$ -	\$ 189.9	\$ -	\$ 189.9	\$ -	\$ 189.9
9.0	2	Ground Data System (GDS)	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -
10.0	2	System Integration, Assembly, Test & Check Out	\$ 28.7	\$ -	\$ -	\$ -	\$ 63.3	\$ -	\$ -	\$ 91.9	\$ -	\$ 91.9
11.0	2	Education & Public Outreach	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -	\$ -
										TOTAL		
										Reserves %		
										0%	\$ 1,944.9	\$ 1,944.9
										Reserves		
												TOTAL w/Fees, Burdens, &
												\$ 1,944.9

Presenting: Nicholas Siodlarz (Chief Engineer)



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Design, Test, and Evaluation (DTE) Scheduling

- Major milestones
 - System assembly concludes 2 years into DTE
 - Testing and evaluation concludes 4.2 years into DTE
 - Launch occurs 4.5 years into DTE
 - Expected primary objective lifetime is 10 years

Milestone	ET (YY:MM:DD)	Milestone	ET (YY:MM:DD)
Components Procurement	00:00:00	Environmental Testing	02:06:00
Sensor Testing	00:03:00	Subsystem V&V	03:04:00
Structure Assembly	01:00:00	System V&V	04:02:00
Structure Testing	01:03:00	Day in the Life Testing	04:02:15
EPS/CDH/GNC/COM Assembly and Integration	02:00:00	Launch Preparation	04:05:00
EPS/CDH/GNC/COM Testing	02:03:00	Flight	04:06:00

Presenting: Nicholas Siodlarz (Chief Engineer)



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Thanks for listening!